



**Universidad Nacional Agraria la Molina**  
**Escuela de Postgrado**  
**Maestría en Ingeniería de Recursos Hídricos**

**Métodos Numéricos en Recursos  
Hídricos**

**Sesión 8:**  
**Diferenciación Numérica**

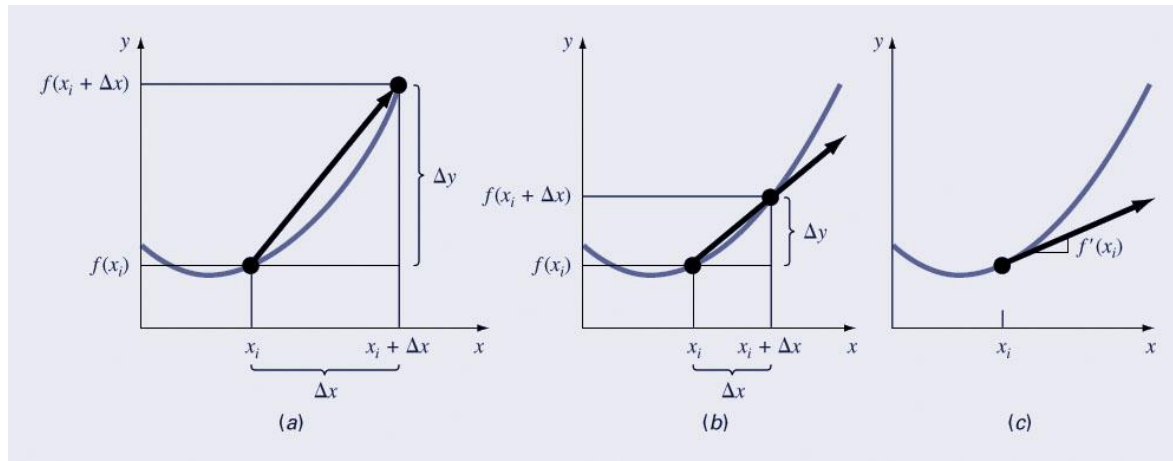
# Diferenciación

- The mathematical definition of a derivative begins with a difference approximation:

$$\frac{\Delta y}{\Delta x} = \frac{f(x_i + \Delta x) - f(x_i)}{\Delta x}$$

and as  $\Delta x$  is allowed to approach zero, the difference becomes a derivative:

$$\frac{dy}{dx} = \lim_{\Delta x \rightarrow 0} \frac{f(x_i + \Delta x) - f(x_i)}{\Delta x}$$



# Backward Finite-Difference

First Derivative

$$f'(x_i) = \frac{f(x_i) - f(x_{i-1})}{h}$$

Error

$O(h)$

$$f'(x_i) = \frac{3f(x_i) - 4f(x_{i-1}) + f(x_{i-2}))}{2h}$$

$O(h^2)$

Second Derivative

$$f''(x_i) = \frac{f(x_i) - 2f(x_{i-1}) + f(x_{i-2}))}{h^2}$$

$O(h)$

$$f''(x_i) = \frac{2f(x_i) - 5f(x_{i-1}) + 4f(x_{i-2}) - f(x_{i-3}))}{h^2}$$

$O(h^2)$

Third Derivative

$$f'''(x_i) = \frac{f(x_i) - 3f(x_{i-1}) + 3f(x_{i-2}) - f(x_{i-3}))}{h^3}$$

$O(h)$

$$f'''(x_i) = \frac{5f(x_i) - 18f(x_{i-1}) + 24f(x_{i-2}) - 14f(x_{i-3}) + 3f(x_{i-4}))}{2h^3}$$

$O(h^2)$

Fourth Derivative

$$f''''(x_i) = \frac{f(x_i) - 4f(x_{i-1}) + 6f(x_{i-2}) - 4f(x_{i-3}) + f(x_{i-4}))}{h^4}$$

$O(h)$

$$f''''(x_i) = \frac{3f(x_i) - 14f(x_{i-1}) + 26f(x_{i-2}) - 24f(x_{i-3}) + 11f(x_{i-4}) - 2f(x_{i-5}))}{h^4}$$

$O(h^2)$

# High-Accuracy Differentiation Formulas

- Taylor series expansion can be used to generate high-accuracy formulas for derivatives by using linear algebra to combine the expansion around several points.
- Three categories for the formula include *forward finite-difference*, *backward finite-difference*, and *centered finite-difference*.

# Forward Finite-Difference

First Derivative

$$f'(x_i) = \frac{f(x_{i+1}) - f(x_i)}{h}$$

Error

$O(h)$

$$f'(x_i) = \frac{-f(x_{i+2}) + 4f(x_{i+1}) - 3f(x_i)}{2h}$$

$O(h^2)$

Second Derivative

$$f''(x_i) = \frac{f(x_{i+2}) - 2f(x_{i+1}) + f(x_i)}{h^2}$$

$O(h)$

$$f''(x_i) = \frac{-f(x_{i+3}) + 4f(x_{i+2}) - 5f(x_{i+1}) + 2f(x_i)}{h^2}$$

$O(h^2)$

Third Derivative

$$f'''(x_i) = \frac{f(x_{i+3}) - 3f(x_{i+2}) + 3f(x_{i+1}) - f(x_i)}{h^3}$$

$O(h)$

$$f'''(x_i) = \frac{-3f(x_{i+4}) + 14f(x_{i+3}) - 24f(x_{i+2}) + 18f(x_{i+1}) - 5f(x_i)}{2h^3}$$

$O(h^2)$

Fourth Derivative

$$f''''(x_i) = \frac{f(x_{i+4}) - 4f(x_{i+3}) + 6f(x_{i+2}) - 4f(x_{i+1}) + f(x_i)}{h^4}$$

$O(h)$

$$f''''(x_i) = \frac{-2f(x_{i+5}) + 11f(x_{i+4}) - 24f(x_{i+3}) + 26f(x_{i+2}) - 14f(x_{i+1}) + 3f(x_i)}{h^4}$$

$O(h^2)$

# Centered Finite-Difference

First Derivative

$$f'(x_i) = \frac{f(x_{i+1}) - f(x_{i-1}))}{2h}$$

Error

$$O(h^2)$$

$$f'(x_i) = \frac{-f(x_{i+2}) + 8f(x_{i+1}) - 8f(x_{i-1}) + f(x_{i-2}))}{12h}$$

$$O(h^4)$$

Second Derivative

$$f''(x_i) = \frac{f(x_{i+1}) - 2f(x_i) + f(x_{i-1}))}{h^2}$$

$$O(h^2)$$

$$f''(x_i) = \frac{-f(x_{i+2}) + 16f(x_{i+1}) - 30f(x_i) + 16f(x_{i-1}) - f(x_{i-2}))}{12h^2}$$

$$O(h^4)$$

Third Derivative

$$f'''(x_i) = \frac{f(x_{i+2}) - 2f(x_{i+1}) + 2f(x_{i-1}) - f(x_{i-2}))}{2h^3}$$

$$O(h^2)$$

$$f'''(x_i) = \frac{-f(x_{i+3}) + 8f(x_{i+2}) - 13f(x_{i+1}) + 13f(x_{i-1}) - 8f(x_{i-2}) + f(x_{i-3}))}{8h^3}$$

$$O(h^4)$$

Fourth Derivative

$$f''''(x_i) = \frac{f(x_{i+2}) - 4f(x_{i+1}) + 6f(x_i) - 4f(x_{i-1}) + f(x_{i-2}))}{h^4}$$

$$O(h^2)$$

$$f''''(x_i) = \frac{-f(x_{i+3}) + 12f(x_{i+2}) + 39f(x_{i+1}) + 56f(x_i) - 39f(x_{i-1}) + 12f(x_{i-2}) + f(x_{i-3}))}{6h^4}$$

$$O(h^4)$$

# Richardson Extrapolation

- The Richardson extrapolation can be used to combine two lower-accuracy estimates of the derivative to produce a higher-accuracy estimate.
- For the cases where there are two  $O(h^2)$  estimates and the interval is halved ( $h_2=h_1/2$ ), an improved  $O(h^4)$  estimate may be formed using:

$$D = \frac{4}{3} D(h_2) - \frac{1}{3} D(h_1)$$

# Unequally Spaced Data

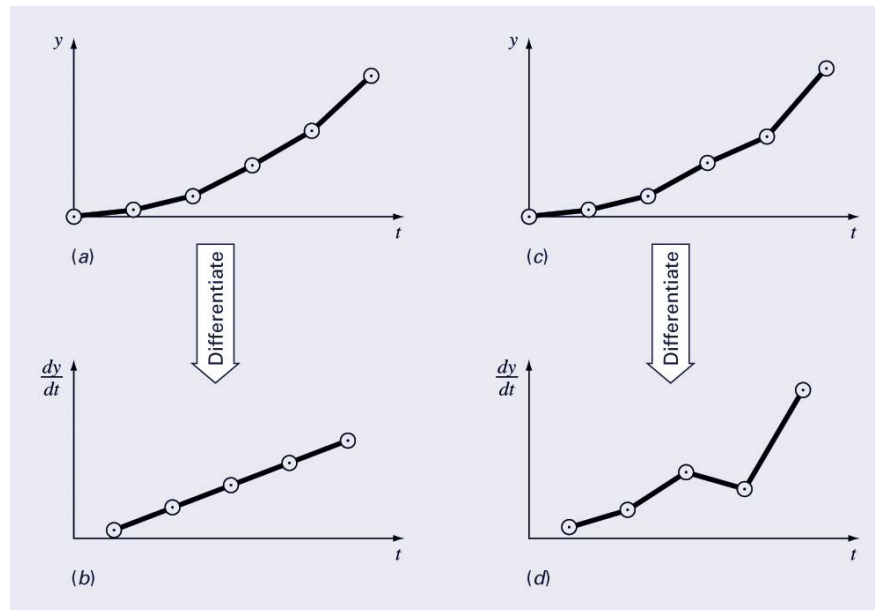
- One way to calculate derivatives of unequally spaced data is to determine a polynomial fit and take its derivative at a point.
- As an example, using a second-order Lagrange polynomial to fit three points and taking its derivative yields:

$$f'(x) = f(x_0) \frac{2x - x_1 - x_2}{(x_0 - x_1)(x_0 - x_2)} + f(x_1) \frac{2x - x_0 - x_2}{(x_1 - x_0)(x_1 - x_2)} + f(x_2) \frac{2x - x_0 - x_1}{(x_2 - x_0)(x_2 - x_1)}$$



# Derivatives and Integrals for Data with Errors

- A shortcoming of numerical differentiation is that it tends to amplify errors in data, whereas integration tends to smooth data errors.
- One approach for taking derivatives of data with errors is to fit a smooth, differentiable function to the data and take the derivative of the function.



# Numerical Differentiation with MATLAB

- MATLAB has two built-in functions to help take derivatives, `diff` and `gradient`:
- `diff(x)`
  - Returns the difference between adjacent elements in `x`
- `diff(y)./diff(x)`
  - Returns the difference between adjacent values in `y` divided by the corresponding difference in adjacent values of `x`

# Numerical Differentiation with MATLAB

- $fx = \text{gradient}(f, h)$   
Determines the derivative of the data in  $f$  at each of the points. The program uses forward difference for the first point, backward difference for the last point, and centered difference for the interior points.  $h$  is the spacing between points; if omitted  $h=1$ .
- The major advantage of `gradient` over `diff` is `gradient`'s result is the same size as the original data.
- Gradient can also be used to find partial derivatives for matrices:  
 $[fx, fy] = \text{gradient}(f, h)$

# Visualization

- MATLAB can generate contour plots of functions as well as vector fields. Assuming  $x$  and  $y$  represent a meshgrid of  $x$  and  $y$  values and  $z$  represents a function of  $x$  and  $y$ ,
  - `contour(x, y, z)` can be used to generate a contour plot
  - `[fx, fy]=gradient(z,h)` can be used to generate partial derivatives and
  - `quiver(x, y, fx, fy)` can be used to generate vector fields